**Yaolin Ge**

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**PERSONAL INFORMATION**

Date of Birth: October 20, 1996

Place of Birth: Shaanxi, China

Citizenship: Chinese

Gender: Male

**EDUCATION**

Aug. 2019 – Present **KTH Royal Institute of Technology, Stockholm, Sweden**

**M.S. Maritime Engineering**

Aug. 2018 – Jun. 2019 **Norwegian University of Science and Technology, Trondheim, Norway**

**G.P.A. 3.93/4.00**

**M.S. Marine Technology**

Sept. 2017 – Jan. 2018 **University of Strathclyde, Glasgow, United Kingdom**

**G.P.A. 3.85/4.00**

**B.S. Naval Architecture & Ocean and Marine Engineering**

Sept. 2014 – Jun. 2018 **Jiangsu University of Science and Technology, Zhenjiang, China**

**G.P.A. 3.89/4.00**

**B.S. Naval Architecture & Ocean Engineering**

**PROJECT EXPERIENCE**

Aug. 2019 – Present **Self-autonomous sailing boat Molly design project**

KTH & SMaRC (Swedish Maritime and Robotic Center), Stockholm, Sweden

* Designed and built the Maribot Vane 2.0, an autonomous sailing vessel
* Engineered and manufactured the glass fibre-made rudder
* Evaluated the mechanical behaviour under certain load contions for most of 3D printed parts as well as parts made from composite materials
* Studied and assessed the performance of the components made from composite materials in terms of weight and strength

Jan. 2019 – Jun. 2019 **Project on numerical analysis of a Wageningen B-screw series propeller**

TMR4220 Naval Hydrodynamics, NTNU, Trondheim

* Analysed the propeller with induction-factor-enhanced lifting line method
* Investigated rake, skew and hub effects on the propeller blade
* Conducted an experimental testing in the towing tank at MARINTEK

Supervisors: Kourosh Koushan, Professor

Aug. 2018 – Dec. 2018 **Project on dynamic & static analysis of marine structures**

TMR4305 Advanced Analysis of Marine Structures, NTNU, Trondheim

* Developed the dynamic response model for a marine riser subjected to waves by use of mode superposition method and analysed the drag forces in both time and frequency domain
* Applied static condensation (concentrated mass) & master-slave (consistent mass) for reduction of number of degrees of freedoms and evaluated the riser performance using frequency response method
* Conducted ABAQUS analysis for an elastic-plastic jacket structure and a stiffened plate and studied the linear buckling analysis and nonlinear ultimate strength analysis

Supervisor: Svein Sævik, Professor; Erin Bachynski, Associate Professor

Jan. 2018 – Jun. 2018 **Research on the added mass effect of VIV for flexible risers**

Bachelor’s thesis, Jiangsu University of Science and Technology, Zhenjiang

* Studied the VIV phenomenon and physics behind VIV and summarised the current research model and developed the time-domain VIV model for low mass ratio system considering added mass effect
* Conducted the sensitivity analysis for different top tension force, current velocity as well as mass ratio working conditions

Supervisor: ZHOU Hong, Professor; WANG Kunpeng, Aassociate Professor

Aug. 2017 – Jan. 2018 **Project on the investigation of flow pattern on a circular cylinder**

NM402 Theory and Practice of Marine CFD, Univ. of Strathclyde, Glasgow

* Studied the vortex shedding phenomenon and physics behind VIV and applied the time-domain VIV model for low mass ratio system
* Reviewed analysis methods such as finite volume method and finite difference method for necessary analysis of computational fluid dynamics
* Simulated the behaviour of the flow pattern for a rigid body circular cylinder under steady flow condition using Star-CCM+

Supervisor: Qing Xiao, Reader; Wendi Liu, Research Associate

**PROFESSIONAL QUALIFICATIONS**

**Personal Skills:**

Programming language with C/C++, Python & MATLAB; FEA analysis using Abaqus & ANSYS APDL; Foil analysis using XFoil; CFD analysis using Star-CCM+; CAD modelling with Solidworks/AutoCAD; Simulation with Simlink (Simevents); 3D FDM printing; Microsoft Office; Latex

**Languages:**

English (fluent)

Chinese (native)

Swedish (conversational)

**AWARDS**

2019 Intel® Edge AI Scholarship, Intel

2019 Best Popular Prize, AI + Art in Robot Dancing Competition, PKU

2017 Merit Student, MOE

2017 First Prize, Academic Competition in Mechanics Knowledge, JUST

2016 – 2017 National Scholarship, MOE

2016 Second Prize Scholarship, CSSC Huangpu Wenchong

2015 National Encouragement Scholarship, MOE

2015 Honourable Mention, Xuediao Structural Innovative Design Contest, JUST

2014 Honourable Mention, CMIH Simulation Model Design Contest, JUST

2014 First Prize, Diesel Engine Assembly & Disassembly Contest, SIYANG

**PROFESSINOAL MEMBERSHIPS**

The Royal Institute of Naval Architects (RINA)

Kongl. Skeppssällskapet

**EXTRA-CURRICULAR**

Jul. 2019 – Aug. 2019 **Project on computer vision for robotic perception**

Peking University, Beijing, China

* Applied OpenPose algorithm to achieve the motion capture activities
* Employed the motion mapping tool to convert 2D motions to 3D skeleton ones
* Programmed Yanshee Robot to dance following human motions

**REFEREES:**

Ivan Stenius Dept. of Aeronautics and Vehicle Engineering, KTH

Associate Professor [stenius@kth.se](mailto:stenius@kth.se) +46 70 288 82 63

Kourosh Koushan Department of Marine Technology, NTNU

Professor [kourosh.koushan@ntnu.no](mailto:kourosh.koushan@ntnu.no) +47 41105297

Tahsin Tezdogan (Ph.D.) Dept. of NAOME, University of Strathclyde

Senior Lecturer [tahsin.tezdogan@strath.ac.uk](mailto:tahsin.tezdogan@strath.ac.uk) +44 (0)141 548 4532

**INTERESTS**

Sailing, running, bicycling, swimming, Taekwondo, cross-country skiing